

Multi-objective Resource Allocation Optimization for SWIPT in Small-cell Networks

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Outline

- 1 Motivation
- 2 System Model
- 3 Joint Transmit Precoding and Receiver Time Switching
SWIPT Design
 - Problem Formulation
 - Algorithm
- 4 Numerical Results
- 5 Conclusion

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Motivation

- Internet of Things (IoT)
 - Battery replacement

Energy harvesting solution
- 5G Networks are excellent opportunities for interconnecting IoTs
 - High network capacity
 - High coverage and available data rates
 - Long handset battery life

Small cell deployment solution
- SWIPT in small cell networks

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System Model

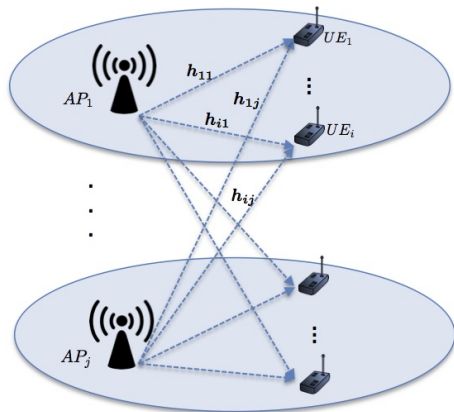


Figure : Multi-AP MISO SWIPT system

Received signal in the i th user

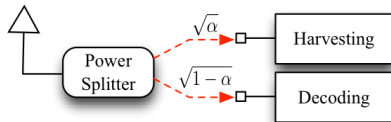
$$y_i = \sum_{j=1}^{N_{AP}} \mathbf{h}_{ij}^H \sum_{l=1}^{N_{UE}} \mathbf{x}_{lj} s_l + n_i$$

System Model

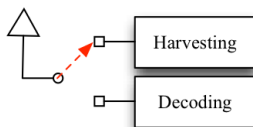
- Colocated Receiver Architecture

- Ideal SWIPT: **Not feasible**

- Power Splitting (PS):



- Time Switching (TS):



System Model

Throughput (bits/sec/Hz) in the TS scheme

$$R_i^{TS}(\mathbf{X}, \alpha_i) = \alpha_i \log_2 \left(1 + \frac{\sum_{j=1}^{N_{AP}} \text{trace}(\mathbf{H}_{ij} \mathbf{X}_{ij})}{\sigma_i^2 + \sum_{j=1}^{N_{AP}} \sum_{l=1, l \neq i}^{N_{UE}} \text{trace}(\mathbf{H}_{ij} \mathbf{X}_{lj})} \right),$$

Harvested Energy (Joule/sec) in the TS scheme

$$E_{h_i}^{TS}(\mathbf{X}, \alpha_i) = (1 - \alpha_i) \eta_i \sum_{j=1}^{N_{AP}} \sum_{l=1}^{N_{UE}} \text{trace}(\mathbf{H}_{ij} \mathbf{X}_{lj}).$$

$$\mathbf{X}_{ij} = \mathbf{x}_{ij} \mathbf{x}_{ij}^H, \mathbf{H}_{ij} = \mathbf{h}_{ij} \mathbf{h}_{ij}^H$$

$$\mathbf{X}_{ij}, \mathbf{H}_{ij} \in \mathbb{C}^{N_{A_j} \times N_{A_j}}, \quad i \in \mathcal{N}_{UE}, j \in \mathcal{N}_{AP}.$$

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Problem Formulation

- Multi-Objective Optimization (MOO)

- $\mathbf{u}_i(\mathbf{X}, \alpha_i) = [R_i^{TS}(\mathbf{X}, \alpha_i), E_{h_i}^{TS}(\mathbf{X}, \alpha_i)]$.

- Problem Formulation

Maximize $\mathbf{u}(\mathbf{X}, \boldsymbol{\alpha})$
 $\mathbf{X}, \boldsymbol{\alpha}$

subject to (1) $\sum_{j=1}^{N_{AP}} \sum_{l=1}^{N_{UE}} \text{trace}(\mathbf{X}_{lj}) \leq P_{max}$

(2) $\mathbf{X}_{lj} \succeq 0, \text{Rank}(\mathbf{X}_{lj}) = 1, \forall l, j$

(3) $\alpha_i \in [0, 1], \forall i$.

Problem Formulation

- SDR (Semidefinite Relaxation) technique
- Weighted Chebyshev scalarization

Maximize λ
 $\mathbf{X}, \alpha, \lambda$

- subject to
- (1) $\alpha_i R_i(\mathbf{X}) \geq \lambda v_i^{(1)}, \forall i$
 - (2) $(1 - \alpha_i) E_i(\mathbf{X}) \geq \lambda v_i^{(2)}, \forall i$
 - (3) $\sum_{j=1}^{N_{AP}} \sum_{l=1}^{N_{UE}} \text{trace}(\mathbf{X}_{lj}) \leq P_{max}$
 - (4) $\mathbf{X}_{lj} \succeq 0, \forall l, j$
 - (5) $\alpha_i \in [0, 1], \forall i.$

Problem Formulation

Maximize λ
 $\mathbf{x}, \alpha_i, \beta_i, R_i, E_i$
 $l_i, \lambda, \forall i$

subject to (C1) $\alpha_i R_i \geq \lambda v_i^{(1)}, \forall i$

(C2) $\beta_i \eta_i E_i \geq \lambda v_i^{(2)}, \forall i$

(C3) $E_i = \sum_{j=1}^{N_{AP}} \sum_{l=1}^{N_{UE}} \text{trace}(\mathbf{H}_{ij} \mathbf{X}_{lj}), \forall i$

(C4) $l_i = \sum_{j=1}^{N_{AP}} \sum_{l=1, l \neq i}^{N_{UE}} \text{trace}(\mathbf{H}_{ij} \mathbf{X}_{lj}), \forall i$

(C5) $R_i = \log(E_i + \sigma_i^2) - \log(l_i + \sigma_i^2), \forall i$

(C6) $\sum_{j=1}^{N_{AP}} \sum_{l=1}^{N_{UE}} \text{trace}(\mathbf{X}_{lj}) \leq P_{max}$

(C7) $\mathbf{X}_{lj} \succeq 0, \forall l, j$

(C8) $\alpha_i + \beta_i = 1, \forall i$

(C9) $\alpha_i \in [0, 1],$

Algorithm

Initialization

Choose an initial point \mathbf{l}_i^0 inside the convex set defined by (C1)-(C4), (C6)-(C9), $\gamma \in \mathbb{R}$ and a given tolerance $\epsilon > 0$.

Convex-concave procedure (CCP)

For a given \mathbf{l}_i^k , solve the convex SDP below to obtain the solution $\hat{\mathbf{l}}_i(\mathbf{l}_i^k)$.

$$\begin{aligned} & \text{Maximize} && \hat{\lambda} \\ & \mathbf{x}, \alpha_i, \beta_i, R_i, E_i \\ & \quad \mathbf{l}_i, \hat{\lambda}, \forall i \\ & \text{subject to} && \text{(C1)-(C4)} \\ & && \text{(C5)} \quad R_i \leq \log(E_i + \sigma_i^2) - \\ & && \left(\log(\mathbf{l}_i^k + \sigma_i^2) + \frac{1}{\mathbf{l}_i^k + \sigma_i^2} (\mathbf{l}_i - \mathbf{l}_i^k) \right) \\ & && \text{(C6)-(C9)} \end{aligned}$$

Termination criteria

If $\|\hat{\mathbf{l}}_i(\mathbf{l}_i^k) - \mathbf{l}_i^k\| \leq \epsilon$
then stop.

Otherwise set
 $\mathbf{l}_i^k = \mathbf{l}_i^k + \gamma(\hat{\mathbf{l}}_i(\mathbf{l}_i^k) - \mathbf{l}_i^k)$.

Proposition 1

The optimal precoding matrices are rank-one.

$$\begin{aligned}\text{Rank}(\mathbf{X}_{lj}) &= 1, \\ \mathbf{X}_{lj} &= \mathbf{x}_{lj}\mathbf{x}_{lj}^H \quad \forall l, j\end{aligned}$$

Proposition 2

CCP Algorithm converges to a *stationary point* of the original problem.

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Numerical Results

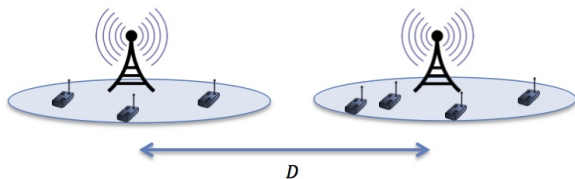


Figure : Simulation scheme

Parameters	Values	Parameters	Values
N_{AP}	2	Pathloss exponent	3
$N_{A_1} = N_{A_2}$	2	σ_i^2	-90 dBm
D	20 m	P_{max}	1 Watt
d_{min}/d_{max}	2/10 m	N_{UE}	2,4,6

Numerical Results

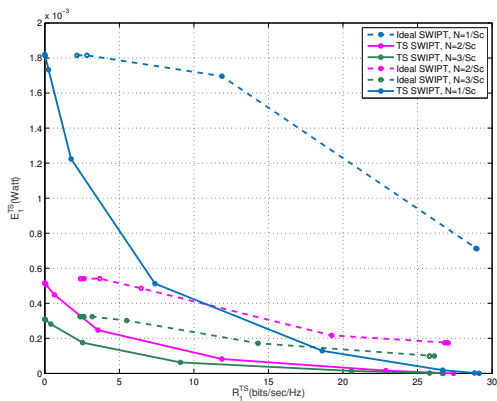
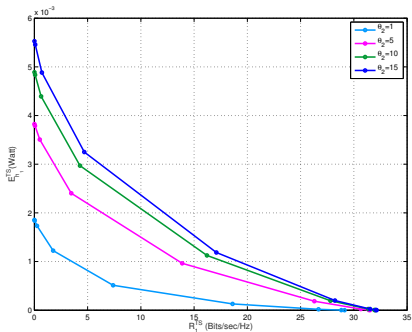
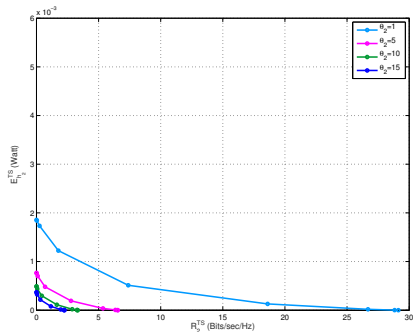


Figure : Pareto frontier of TS SWIPT and ideal SWIPT,
 $v_i^{(1)} = \theta_1, v_i^{(2)} = 1 \forall i$

Numerical Results



(a)



(b)

Figure : Pareto frontier of first and second TS SWIPT UEs with different priorities,

$$v_1^{(1)} = \theta_1 \theta_2, v_1^{(2)} = \theta_2 \text{ and } v_2^{(1)} = \theta_1, v_2^{(2)} = 1$$

Numerical Results

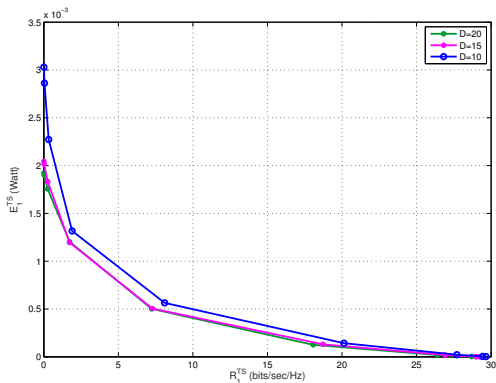


Figure : Pareto frontier of TS SWIPT for different AP distances

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Conclusion

- Joint Transmit Precoding and Receiver Time Switching SWIPT Design was formulated as an MOO problem and solved using CCP Algorithm.
- Numerical results show that:
 - The loss due to TS SWIPT decreases with increasing the number of users.
 - Coordination between cells can be used to drastically increase the energy harvested of one user at the expense of the other user's performance.
 - Interference can be exploited to increase the amount of harvested energy while not degrading the data rate.

References



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Thank you for your attention!